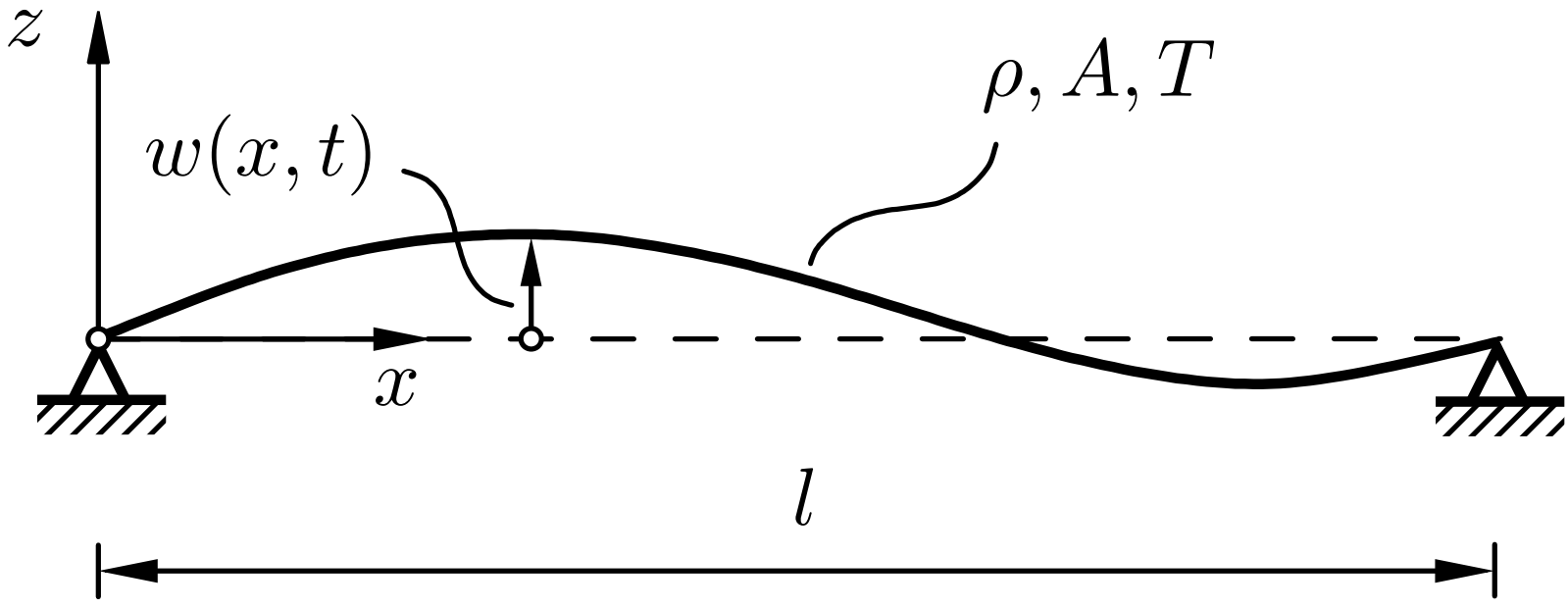
z
$w(x,t)$
ρ, A, T
x
l